#### **The constrained Block-PARAFAC decomposition**

André de Almeida $^1$ , Gérard Favier $^1$  and João Mota $^2$ 

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. . . lima@i3s.unice.fr, favier@i3s.unice.fr, mota@deti.ufc.br

www.i3s.unice.fr/∼lima

 $^1$ I3S Laboratory, University of Nice-Sophia Antipolis, France  $2$ Department of Teleinformatics Engineering, Federal University of Ceara, Brazil

#### Presentation outline

- $\bullet$ • Motivations and preliminaries
- $\bullet$ • Constrained Block-PARAFAC formulation
- $\bullet$ • Some terminology and concepts
- $\bullet$ • Link: constrained Block-PARAFAC and Block-Tucker3
- $\bullet$ Uniqueness issues
- $\bullet$ Applications in wireless signal processing
- $\bullet$ Concluding remarks and perspectives

## Motivations and preliminaries

#### **Acknowledgement:**

To Richard Harshman for his valuable comments, suggestions and motivation on important issues of this work.

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- •• PARAFAC: no interaction between modes, unique (without orthogonality constraints);
- $\bullet$ Tucker3: complete interaction between modes, *nonunique* (rotational indeterminacy);
- • Mixed PARAFAC-Tucker3 models [Bro'98]:
	- ∗ Constrained interactions involving factors different modes (not as complete as in Tucker3 models);
	- ∗ Arise in some wireless signal processing problems:
		- Multiantenna codings
		- Blind beamforming

## Motivations and preliminaries

- $\bullet$ **• Mixed PARAFAC-Tucker3 decompositions:** 
	- ∗ Thinking "Tucker3-wise": constrained core tensor
	- ∗ Thinking "PARAFAC-wise": constrained factor matrices
- $\bullet$  Generalizing/combining PARAFAC and Tucker3 decompositions:
	- ∗ Decomposition in <sup>a</sup> sum of smaller Tucker3 blocks: [De Lathauwer'05]
	- ∗ Decomposition in <sup>a</sup> sum of constrained PARAFAC blocks: Special case of [De Lathauwer'05]

 $\bullet$ • The decomposition in scalar form  $\mathcal{X} \in \mathbb{C}^{I_1 \times I_2 \times I_3}$ , Q blocks):

$$
x_{i_1,i_2,i_3} = \sum_{q=1}^{Q} \sum_{r_1^{(q)}=1}^{R_1^{(q)}} \sum_{r_2^{(q)}=1}^{R_2^{(q)}} a_{i_1,r_1^{(q)}}^{(q)} b_{i_2,r_2^{(q)}}^{(q)} c_{r_1^{(q)},r_2^{(q)},i_3}^{(q)}.
$$

Special case of [De Lathauwer'05];

$$
\bullet \ \{\mathbf{A}^{(q)}\} \in \mathbb{C}^{I_1 \times R_1^{(q)}} \text{ and } \{\mathbf{B}^{(q)}\} \in \mathbb{C}^{I_2 \times R_2^{(q)}}, \ \{\mathcal{C}^{(q)}\} \in \mathbb{C}^{R_1^{(q)} \times R_2^{(q)} \times I_3}
$$

• Set of matrices  $\{ \mathbf{C}^{(q)} \} \in \mathbb{C}^{I_3 \times R_1^{(q)} R_2^{(q)}}$  defined as:

$$
\left[\mathbf{C}^{(q)}\right]_{i_3,(r_1^{(q)}-1)R_2^{(q)}+r_2^{(q)}}=c_{r_1^{(q)},r_2^{(q)},i_3}^{(q)}, q=1,\ldots,Q
$$

 $\bullet$ • Factorization as a sum of constrained PARAFAC blocks [de Almeida et al.'05]:

$$
\mathbf{X}_{\cdot \cdot i_3} = \sum_{q=1}^Q \left( \mathbf{A}^{(q)} \otimes \mathbf{1}_{R_2^{(q)}}^T \right) D_{i_3}(\mathbf{C}^{(q)}) \left( \mathbf{1}_{R_1^{(q)}}^T \otimes \mathbf{B}^{(q)} \right)^T.
$$

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#### Interaction patterns

• Equivalences:

$$
\mathbf{A}^{(q)} \otimes \mathbf{1}_{R_2^{(q)}}^T = (\mathbf{A}^{(q)} \otimes 1)(\mathbf{I}_{R_1^{(q)}} \otimes \mathbf{1}_{R_2^{(q)}}^T) = \mathbf{A}^{(q)}(\underbrace{\mathbf{I}_{R_1^{(q)}} \otimes \mathbf{1}_{R_2^{(q)}}^T}_{\mathbf{\Psi}^{(q)}}) = \mathbf{A}^{(q)}\mathbf{\Psi}^{(q)};
$$

1<sup>T</sup> <sup>R</sup>(q) 1 <sup>⊗</sup>B(q) <sup>=</sup> (1⊗B(q))(1TR(q) <sup>1</sup> <sup>⊗</sup>IR(q) <sup>2</sup> ) <sup>=</sup> <sup>B</sup>(q)(1TR(q) <sup>1</sup> <sup>⊗</sup> <sup>I</sup>R(q) <sup>2</sup> | {z } Φ(q) ) <sup>=</sup> <sup>B</sup>(q)Φ(q);

• Constraint matrices:

$$
\bm{\Psi}^{(q)} = \mathbf{I}_{R_1^{(q)}} \otimes \bm{1}_{R_2^{(q)}}^T, \qquad \bm{\Phi}^{(q)} = \bm{1}_{R_1^{(q)}}^T \otimes \mathbf{I}_{R_2^{(q)}}
$$

• The sets  $\{\mathbf \Psi^{(1)},\ldots,\mathbf \Psi^{(Q)}\}$  and  $\{\mathbf \Phi^{(1)},\ldots,\mathbf \Phi^{(Q)}\}$  reveal the interaction patterns within the different blocks;

• Factorization using the constraint matrices

$$
\mathbf{X}_{\cdot \cdot i_3} = \sum_{q=1}^{Q} \mathbf{A}^{(q)} \mathbf{\Psi}^{(q)} D_{i_3}(\mathbf{C}^{(q)}) (\mathbf{B}^{(q)} \mathbf{\Phi}^{(q)})^T.
$$

• Block factor matrices:

$$
\mathbf{A} = [\mathbf{A}^{(1)}, \dots, \mathbf{A}^{(Q)}] \in \mathbb{C}^{I_1 \times R_1}
$$
  

$$
\mathbf{B} = [\mathbf{B}^{(1)}, \dots, \mathbf{B}^{(Q)}] \in \mathbb{C}^{I_2 \times R_2}
$$
  

$$
\mathbf{C} = [\mathbf{C}^{(1)}, \dots, \mathbf{C}^{(Q)}] \in \mathbb{C}^{I_3 \times R_3},
$$

$$
R_1 = \sum_{q=1}^{Q} R_1^{(q)}, \quad R_2 = \sum_{q=1}^{Q} R_2^{(q)}, \quad R_3 = \sum_{q=1}^{Q} R_1^{(q)} R_2^{(q)}.
$$

• Block constraint matrices:

$$
\begin{array}{rcl}\n\mathbf{\Psi} & = & BlockDiag(\mathbf{\Psi}^{(1)} \cdots \mathbf{\Psi}^{(Q)}) \quad (R_1 \times R_3) \\
\mathbf{\Phi} & = & BlockDiag(\mathbf{\Phi}^{(1)} \cdots \mathbf{\Phi}^{(Q)}) \quad (R_2 \times R_3)\n\end{array}
$$

•Compact matrix-slice form:

$$
\mathbf{X}_{\cdot \cdot i_3} = \mathbf{A} \mathbf{\Psi} D_{i_3}(\mathbf{C})(\mathbf{B} \mathbf{\Phi})^T.
$$

•• Unfolded matrices:

 $\mathbf{X}_1 = (\mathbf{C}{\diamond}\mathbf{A}\mathbf{\Psi})(\mathbf{B}\mathbf{\Phi})^T, \quad \mathbf{X}_2 = (\mathbf{B}\mathbf{\Phi}{\diamond}\mathbf{C})(\mathbf{A}\mathbf{\Psi})^T, \quad \mathbf{X}_3 = (\mathbf{A}\mathbf{\Psi}{\diamond}\mathbf{B}\mathbf{\Phi})\mathbf{C}^T$ 

Related to PARALIND models [Bro-Harsh-Sid'05]

• Expansion using tensor products of canonical vectors: Goal: Justify the introduction of the constraint matrices [de Almeida et al.'06]

$$
\mathbf{X}_{3} = \sum_{i_{1}=1}^{I_{1}} \sum_{i_{2}=1}^{I_{2}} \sum_{i_{3}=1}^{I_{3}} x_{i_{1},i_{2},i_{3}} (e_{i_{1}}^{(I_{1})} \otimes e_{i_{2}}^{(I_{2})}) e_{i_{3}}^{(I_{3})T}
$$

$$
\mathbf{X}_{3} = \sum_{i_{1}=1}^{I_{1}} \sum_{i_{2}=1}^{I_{2}} \sum_{i_{3}=1}^{I_{3}} \sum_{q=1}^{I_{3}} \sum_{r_{1}=1}^{Q} \sum_{r_{2}=1}^{R_{1}} \sum_{r_{1}=1}^{R_{2}} a_{i_{1},r_{1}}^{(q)} b_{i_{2},r_{2}}^{(q)} c_{r_{1},r_{2},i_{3}}^{(q)} (e_{i_{1}}^{(I_{1})} \otimes e_{i_{2}}^{(I_{2})}) e_{i_{3}}^{(I_{3})T}
$$

## Some terminology and concepts

What can be said about constrained Block-PARAFAC ?

- Factorization of a three-way array in a sum of  $Q$  constrained PARAFAC blocks, everyone of them being <sup>a</sup> function of three component matrices  $\mathbf{A}^{(q)}$ ,  $\mathbf{B}^{(q)}$  and  $\mathbf{C}^{(q)}$ .
- Within the same PARAFAC block, it is permitted that columns of different component matrices are linearly combined to generate the three-way data.
- The interaction pattern is defined by the matrices  $\mathbf{\Psi}^{(q)}$  and  $\mathbf{\Phi}^{(q)}$ and may differ from block to block.
- No interaction takes place between blocks.

## Some terminology and concepts

"Between-block" *versus* "Within-block" uniqueness: [Terms coined by Harshman]

 $\bullet$ Uniqueness concepts interpreted in two ways:

 $\ast$  *Between-block uniqueness*: synonym of *separability* of the  $Q$ blocks. Independent of the interaction structure.

∗ Within-block uniqueness: unique determination of the three component matrices of the corresponding block (up to permutation and scaling). Dependent of the particular interaction structure.

- $\bullet$ • Connection with "partial" uniqueness concepts:
	- ∗ PARAFAC case [Harshman'72] [ten Berge'04] [Bro-Harsh-Sid'05]:

"When non-unique solutions occur ... uniqueness can partially or completely "break down"..." [Harshman'72]

∗ Constrained Block-PARAFAC case:

Uniqueness can break down "in parts" (within <sup>a</sup> block)... but also "between blocks"!

# Constrained Block-PARAFAC *linked to* Block- $Tncker^2$

•• Constrained Block-PARAFAC can be approached to Tucker3 analysis [Kiers&Smilde'98] [ten Berge&Smilde'02]:

**Proposition:** The constrained Block-PARAFAC decomposition is equivalent to a "constrained Block-Tucker3" one, where the unfolded matrices of the every core tensor block are column-wise orthogonal, i.e., the inner product of any two distinct columns of every unfolded core matrix is equal to zero.

• The link relies on the concept of block Khatri-Rao product | <sup>⊗</sup> | :  $\mathbf{A} \ [\otimes] \ \mathbf{B} = [\mathbf{A}^{(1)} {\otimes} \mathbf{B}^{(1)}, \cdots, \mathbf{A}^{(Q)} {\otimes} \mathbf{B}^{(Q)}].$ 

$$
\mathbf{X}_3 = (\mathbf{A}\mathbf{\Psi} \diamond \mathbf{B}\mathbf{\Phi})\mathbf{C}^T = (\mathbf{A} \otimes \mathbf{B})F(\mathbf{\Psi}, \mathbf{\Phi})\mathbf{C}^T.
$$

$$
F(\mathbf{\Psi}, \mathbf{\Phi}) = BlockDiag(\mathbf{\Psi}^{(1)} \diamond \mathbf{\Phi}^{(1)} \cdots \mathbf{\Psi}^{(Q)} \diamond \mathbf{\Phi}^{(Q)})
$$

$$
\mathbf{I}_{R_3^{(1)}} \qquad \mathbf{I}_{R_3^{(Q)}}
$$

$$
\Rightarrow \mathbf{X}_3 = (\mathbf{A} \otimes \mathbf{B})\mathbf{G}_3\mathbf{C}^T, \quad \mathbf{G}_3 = \mathbf{I}_{R_3}
$$

(Constrained Block-Tucker3 decomp.)

#### Constrained Block-PARAFAC *linked to* Block-Tucker3<u> 1980 - Johann Barn, amerikan besteman besteman besteman besteman besteman besteman besteman besteman bestema</u>

• Unfolded matrices  $\mathbf{X}_1$  and  $\mathbf{X}_2$ :

$$
\mathbf{X}_1=(\mathbf{C}\mid \textcolor{black}{\otimes} \mid \mathbf{A})\mathbf{G}_1\mathbf{B}^T, \qquad \mathbf{X}_2=(\mathbf{B}\mid \textcolor{black}{\otimes} \mid \mathbf{C})\mathbf{G}_2\mathbf{A}^T,
$$

• Unfolded block-cores  $\mathbf{G}_1$  and  $\mathbf{G}_2$ :

$$
\mathbf{G}_{1} = BlockDiag(\mathbf{G}_{1}^{(1)} \cdots \mathbf{G}_{1}^{(Q)}) \in \mathbb{C}^{R^{'} \times R_{2}},
$$
\n
$$
\mathbf{G}_{2} = BlockDiag(\mathbf{G}_{2}^{(1)} \cdots \mathbf{G}_{2}^{(Q)}) \in \mathbb{C}^{R^{''} \times R_{1}},
$$
\n
$$
R^{'} = \sum_{q=1}^{Q} R_{1}^{(q)} R_{3}^{(q)}, \quad R^{''} = \sum_{q=1}^{Q} R_{2}^{(q)} R_{3}^{(q)}
$$
\n
$$
\mathbf{G}_{1}^{(q)} = (\mathbf{I}_{R_{3}^{(q)}} \diamond \mathbf{\Psi}^{(q)}) \mathbf{\Phi}^{(q)T}, \quad \mathbf{G}_{2}^{(q)} = (\mathbf{\Phi}^{(q)} \diamond \mathbf{I}_{R_{3}^{(q)}}) \mathbf{\Psi}^{(q)T}
$$
\n• Are  $\mathbf{G}_{1}^{(q)}$  and  $\mathbf{G}_{2}^{(q)}$  column-wise orthogonal ?

# Constrained Block-PARAFAC *linked to* Block-Tucker3

• We have:

$$
\mathbf{G}_1^{(q)T}\mathbf{G}_1^{(q)} = \mathbf{\Phi}^{(q)}\mathbf{\Phi}^{(q)T} = R_1^{(q)}\mathbf{I}_{R_2^{(q)}}
$$

$$
\mathbf{G}_2^{(q)T}\mathbf{G}_2^{(q)} = \mathbf{\Psi}^{(q)}\mathbf{\Psi}^{(q)T} = R_2^{(q)}\mathbf{I}_{R_1^{(q)}}
$$

 $\bullet$  $\bullet~$  Column-wise orthogonality also for  $\mathbf{G}_{1}$  and  $\mathbf{G}_{2}$ 

Constraint matrices from <sup>a</sup> PARAFAC perspective give rise to orthogonal tensor cores from <sup>a</sup> Tucker3 perspective

- $\bullet$  Uniqueness proof of constrained Block-PARAFAC relies on Harshman's original proof of "minimum conditions" for PARAFAC [Harshman'72].
- •• The proof sheds light on the between-block resolution/separability for constrained Block-PARAFAC.
- • Within-block uniqueness can be studied separately for each block, possibly taking special (within-block) structures into account.
- • Different levels of "partial" uniqueness are possible for constrained Block-PARAFAC

**Theorem**: Assuming full rank  $\mathbf{A}^{(q)} \in \mathbb{C}^{I_1 \times R_1^{(q)}}$ ,  $\mathbf{B}^{(q)} \in \mathbb{C}^{I_2 \times R_2^{(q)}}$  and  $\mathbf{C}^{(q)} \in \mathbb{C}^{I_3 \times R_1^{(q)}R_2^{(q)}}$ ,  $q = 1, \ldots, Q$ , and linear independency of every set  ${A^{(1)}, \ldots, A^{(Q)}}, {B^{(1)}, \ldots, B^{(Q)}}$  and  ${C^{(1)}, \ldots, C^{(Q)}}$ , if:

$$
I_1 I_2 \ge \sum_{q=1}^{Q} R_1^{(q)} R_2^{(q)}, \quad I_1 I_3 \ge \sum_{q=1}^{Q} R_2^{(q)}, \quad I_2 I_3 \ge \sum_{q=1}^{Q} R_1^{(q)}.
$$

between-block uniqueness is achieved and  $\mathbf{A} = \mathbf{A}\mathbf{T}_a,$   $\mathbf{B} = \mathbf{B}\mathbf{T}_b$  and  $\mathbf{C} = \mathbf{CT}_c$  (up to permutation ambiguities).

$$
\mathbf{T}_a = BlockDiag(\mathbf{T}_a^{(1)} \cdots \mathbf{T}_a^{(Q)}),
$$
  
\n
$$
\mathbf{T}_b = BlockDiag(\mathbf{T}_b^{(1)} \cdots \mathbf{T}_b^{(Q)}),
$$
  
\n
$$
\mathbf{T}_c = BlockDiag(\mathbf{T}_c^{(1)} \cdots \mathbf{T}_c^{(Q)}),
$$

$$
\left(\mathbf{T}_a^{(q)} \otimes \mathbf{T}_b^{(q)}\right)^{-1} = \mathbf{T}_c^{(q)T}, \quad q = 1, \dots, Q
$$

- $\bullet$ • Rotational freedom confined within the blocks; (due to block-diagonal structure of  $\mathbf{T}_a$ ,  $\mathbf{T}_b$  and  $\mathbf{T}_c$ )
- •• Within-block rotational freedom is constrained; (not as complete as for Tucker3)
- $\bullet$ Recovering of complete within-block uniqueness  $(q$ -th block):  $*$  If  $\mathbf{C}^{(q)}$  is known  $\Rightarrow \mathbf{T}^{(q)}_a \otimes \mathbf{T}^{(q)}_b = \mathbf{I};$ 
	- $\ast$  If rotational indeterminacy  $\mathbf{T}^{(q)}_{c}$  is fixed;
- •• Partial uniqueness arises if a subset of  $\{ {\bf T}^{(1)}_a, \ldots, {\bf T}^{(Q)}_a \}$  or  $\{ {\bf T}_b^{(1)}, \ldots, {\bf T}_b^{(Q)} \}$  is fixed.

Blocks with equal interaction patterns

$$
R_1^{(1)} = \ldots = R_1^{(Q)} = \overline{R}_1
$$
 and  $R_2^{(1)} = \ldots = R_2^{(Q)} = \overline{R}_2$ 

• Equivalent necessary condition:

$$
min\left(\lfloor \frac{I_1I_2}{\overline{R}_1\overline{R}_2} \rfloor, \lfloor \frac{I_1I_3}{\overline{R}_2} \rfloor, \lfloor \frac{I_2I_3}{\overline{R}_1} \rfloor \right) \ge Q.
$$

• For  $R_1 = R_2 = 1$  (standard PARAFAC) the above condition reduces to the necessary uniqueness conditions of [Liu-Sid'01].

# Partial uniqueness in constrained Block-PARAFA

- Some blocks can be uniquely determined, while the remaining ones are either nonunique or partially unique ⇒ (breaking down of uniqueness **between** blocks)
- •• For the remaining (no strictly unique) blocks:

#### Situation 1: Within-block nonuniqueness

All the corresponding component matrices affected by unknown rotational indeterminacy;

#### Situation 2: Within-block partial uniqueness

Some component matrices (or <sup>a</sup> subset of their columns) uniquely determined ⇒ (breaking down of uniqueness **within** <sup>a</sup> block)

# Partial uniqueness in constrained Block-PARAFAC

#### Example 1:

#### $Q = 3$  blocks  $\{R^{(1)}_1, R^{(1)}_2\} = \{1,1\}, \quad \{{\bf a}^{(1)},{\bf b}^{(1)},{\bf c}^{(1)}\}$  $\{R^{(2)}_1, R^{(2)}_2\} = \{2,2\},\quad \{{\bf A}^{(2)},{\bf B}^{(2)},{\bf C}^{(2)}\}$  $\{R^{(3)}_1, R^{(3)}_2\} = \{1,2\}, \quad \{{\bf a}^{(3)},{\bf B}^{(3)},{\bf C}^{(3)}\}$

Block-constraint matrices:

$$
\Psi = \left[ \begin{array}{cccccc} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{array} \right], \quad \Phi = \left[ \begin{array}{cccccc} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{array} \right]
$$

Block 1: *unique (* Block 2: *nonunique (* Block 3: *partially unique*  $\big/\left(\mathbf{T}^{(2)}_a\otimes\mathbf{T}^{(2)}_b\right)^{-1}=\mathbf{T}^{(2)T}_c\big/\qquad \mathbf{T}^{(3)T}_b=\mathbf{T}^{(3)-1}_c$ 

# Partial uniqueness in constrained Block-PARAFAC

#### Example 2:

 $Q = 3$  blocks  $\{R^{(1)}_1, R^{(1)}_2\} = \{1,2\}, \quad \{{\bf a}^{(1)},{\bf B}^{(1)},{\bf C}^{(1)}\}$  $\{R^{(2)}_1, R^{(2)}_2\} = \{1,2\}, \quad \{{\bf a}^{(2)},{\bf B}^{(2)},{\bf C}^{(2)}\}$  $\{R^{(3)}_1, R^{(3)}_2\} = \{1,2\}, \quad \{{\bf a}^{(3)},{\bf B}^{(3)},{\bf C}^{(3)}\}$ 

Block-constraint matrices:  $\Psi = \bigg[$  $\begin{array}{c} \hline \end{array}$ 1 1 0 0 0 0 0 0 1 1 0 0  $\left[ \begin{array}{ccccccc} 0 & 0 & 1 & 1 & 0 & 0 \ 0 & 0 & 0 & 0 & 1 & 1 \end{array} \right] \,, \quad \Phi =$   $\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 &$  0 1 0 0 0 0 0 0 1 0 0 0 0 0 0 1 0 0 0 0 0 0 1 0 0 0 0 0 0 1  $\overline{\phantom{a}}$ 

- $\Rightarrow$  Partial uniqueness in all the blocks
- $\Rightarrow$  Complete uniqueness in the first-mode

This case coincides with the "FIA PARALIND model" [Bro-Harsh-Sid'05]

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# Applications in Wireless Signal Processing

 $\bullet$ **• Some previous works using PARAFAC modeling in wireless** communications:

(DS-CDMA, OFDM, blind beamforming, multiantenna (MIMO) systems,...)

[Sidiropoulos et al.'00-1] [Sidiropoulos et al.'00-2] [Sidiropoulos&Dimic'01], [Sidiropoulos&Liu'01] [Sidiropoulos&Budampati'02] [Jiang&Sidiropoulos'03] [de Baynast&De Lathauwer'03] [de Baynast et al.'03] [De Lathauwer'05]

- • Two classes of wireless communication problems formulated using constrained Block-PARAFAC modeling:
	- ∗ Multiantenna coding

(with spatial spreading and single-antenna multiplexing)

∗ Blind beamforming

(under specular propagation and large delay spread)

 $\bullet$  Constrained Block-PARAFAC structure arises in some of previous works while generalizing some previously proposed three-way models

# Application 1: Multiantenna coding





**Three-way array dimensions**:

 $I_1=M_R:\,$  Nb. of receive antennas

 $I_2=N: \;\;$  Nb. of time-slots

 $I_3 = P:\quad$  Nb. of coded symbols per time-slot (code length)

#### **Model parameters**:

 $Q$ : Nb. of transmission groups (or users to be served)  $R_1^{\left( q \right)} = L^{\left( q \right)}$ : Nb. spatially-multiplexed signals  $R_{2}^{\left(q\right)}=M_{T}^{\left(q\right)}$ : Nb. of spreading transmit antennas  $_{\sf A}$ de Almeida et al. / TRICAP2006 – June 05, 2006 – p.22

## Application 1: Multiantenna coding



nosition of the received signal as a three-way ar •

$$
x_{m_R,n,p} = \sum_{q=1}^{Q} \sum_{m_T^{(q)}=1}^{M_T^{(q)}} h_{m_R,m_T^{(q)}}^{(q)} \sum_{l^{(q)}=1}^{L^{(q)}} s_{n,l^{(q)}}^{(q)} w_{m_T^{(q)},l^{(q)},p}^{(q)} + v_{m_R,n,p}
$$

 $x_{m_R,n,p} = [\mathcal{X}]_{m_R,n,p}$  : received signal  $h^{(q)}$  $\binom{(q)}{m_R,m_T^{(q)}} = \left[\mathbf{H}^{(q)}\right]_{m_R,m_T^{(q)}}: \text{ $q$-th MIMO channel}$  $s_{n,l(q)}^{(q)} = [\mathbf{S}^{(q)}]_{n,l(q)}$  : transmitted symbols (during the n-th time-slot)  $w^{(q)}$  $\binom{(q)}{m^{(q)}_T,l^{(q)},p} = \big[\mathbf{W}^{(q)}\big]_{p,(l^{(q)}-1)M^{(q)}_T+l^{(q)}}:$  coding/multiplexing tensor

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# Application 1: Multiantenna coding

 $*$   $L'=L^{(1)}+\cdots+L^{(Q)}:$  total number of multiplexed signals  ${}^*M_T' = M_T^{(1)} + \cdots + M_T^{(Q)}: \;\;$  total number of transmit antennas  ${}^*R'=L^{(1)}M_T^{(1)}+\cdots+ L^{(Q)}M_T^{(Q)}: \;\;$  number of columns of  $\bf W$ 

 $\bullet$ • Constrained Block-PARAFAC model:  $(\mathbf{H} \in \mathbb{C}^{M_R \times M'_T}, \quad \mathbf{S} \in \mathbb{C}^{N \times L'}, \quad \mathbf{W} \in \mathbb{C}^{P \times R'}).$ 

$$
\mathbf{X} = (\mathbf{H}\Psi \diamond \mathbf{S}\Phi)\mathbf{W}^T + \mathbf{V}, \qquad \mathbf{W}\mathbf{W}^H = M'_T \mathbf{I}_P
$$

• Constrained Block-PARAFAC model covers some multi-antenna coding schemes as special cases:

 ${}_* \, L^{(q)} = M_T^{(q)} = 1, \quad Q > 1:$ 

Reduces to the multiantenna code of [Sidiropoulos&Budampati'02]

$$
* Q = 1, \quad L^{(q)} > 1, M_T^{(q)} > 1:
$$

Takes the form of the multiantenna code of [Hassibi'02]

## Constraint matrices: *Physical interpretation*

- ••  $\Psi$  and  $\Phi$  can be seen as symbol-to-antenna loading matrices
- $\bullet$ • Reveal the *joint spreading-multiplexing pattern* considered at the transmitter, for each transmission group;
- By configuring the joint pattern of 1's and 0's of these matrices  $\rightarrow$  different multiantenna coding schemes can be constructed

#### Example:

 $\overline{M}_T'=3$  transmit antennas,  $Q=2$  Tx groups.

Spreading-multiplexing structures:  $(M^{(1)}_T, L^{(1)}) = (2,1)$  and  $(M^{(2)}_T, L^{(2)}) = (1,3).$ 

$$
\Psi = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 \end{bmatrix} \in \mathbb{C}^{M'_T \times R'}, \quad \Phi = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \in \mathbb{C}^{L' \times R'}
$$

1) Rows of  $\Psi$  reveal the spatial *multiplexing factor* 

 $\Rightarrow$  nb. of symbols simultaneously loaded at the same transmit antenna

- 2) Rows of  $\Phi$  reveal the spatial spreading factor
	- $\Rightarrow$  nb. of transmit antennas simultaneously transmitting the same symbol

### Constraint matrices: *Physical interpretation*

Joint spreading-multiplexing pattern: The matrix product  $\Psi \Phi^T$ 

$$
\mathbf{\Psi}\mathbf{\Phi}^T = \left[ \begin{array}{cccc} 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{array} \right] \in \mathbb{C}^{M_T' \times L'}
$$

- Reading  $\mathbf{\Psi} \mathbf{\Phi}^T$  column-wise (for a fixed row):
	- ∗ check for the nb. of data-streams multiplexed at <sup>a</sup> given antenna
- Reading  $\mathbf{\Psi} \mathbf{\Phi}^T$  row-wise (for a fixed column):
	- ∗ check for the nb. of antennas spreading <sup>a</sup> given data-stream

**Remark:** Symbol-to-antenna allocation obtained by permuting the columns of the constraint matrices  $\boldsymbol{\Psi}$  and  $\boldsymbol{\Phi}.$  Important in spatially correlated channels

#### Constrained Block-PARAFAC based multi-

#### antenna receiver



Rate ( $q$ -th group) =  $(L^{(q)}/P)log_2(\mu)$  bits/channel use



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# Application 2: Blind Beamforming



#### **Three-way array dimensions**:

 $I_1 = M:\,$  Nb. of receiver antennas

 $I_2=N:\;$  Nb. of symbols periods

 $I_3 = P: ~$  Oversampling factor (nb. of samples/symbol period)

#### **Model parameters**:

 $Q$ : Nb. of source signals  $R_1^{(q)} = L^{(q)}$ : Nb. of multipaths ( $q$ -th source);  $\; L' = L^{(1)} + \cdots + L^{(Q)}$  $R_2^{\left( q\right) }=K\colon \;$  Temporal support of the convolutive channel (common for all sources)

# Application 2: Blind Beamforming

•Decomposition of the received signal as <sup>a</sup> three-way array:

$$
x_{m,n,p} = \sum_{q=1}^{Q} \sum_{l^{(q)}=1}^{L^{(q)}} b_{l^{(q)}}^{(q)} a_{m,l^{(q)}}^{(q)} \sum_{k=1}^{K} s_{n,k}^{(q)} g_{l^{(q)},k,p}^{(q)} + v_{m,n,p}
$$

 $x_{m,n,p} = [\mathcal{X}]_{m,n,p}$  : received signal

 $b_{l(q)}^{(q)} = [Diag(\mathbf{B}^{(q)})]_{l(q),l(q)}$  : multipath gains/amplitudes  $a_{m,l(q)}^{(q)} = a_m^{(q)}(\theta_{l(q)}) = [\mathbf{A}^{(q)}]_{m,l(q)}$  array response (Vandermonde structure)  $g_{\iota(q)-k,n}^{(q)} = g(k-1+(p-1)/P - \tau_{l^{(q)}}) = [\mathbf{G}^{(q)}]_{p,(l^{(q)}-1)K+k}$  pulse shape  $s_{n,k}^{(q)} = [\mathbf{S}^{(q)}]_{n,k}$  : transmitted symbols (Toeplitz structure)

• Constrained Block-PARAFAC model:  $(A \in \mathbb{C}^{M \times L'}, \quad S \in \mathbb{C}^{N \times QK}, \quad H \in \mathbb{C}^{P \times L'K}$ 

 $\mathbf{X} = (\mathbf{A}\mathbf{\Psi} \diamond \mathbf{S}\mathbf{\Phi})\mathbf{H}^T + \mathbf{V}, \quad \mathbf{H} = \mathbf{G}(\mathbf{B} \otimes \mathbf{I}_K)$  $\Psi = BlockDiag(\mathbf{I}_{L^{(1)}}\otimes \mathbf{1}_K^T\cdots \mathbf{I}_{L^{(Q)}}\otimes \mathbf{1}_K^T)$  $\boldsymbol{\Phi} = BlockDiag(\mathbf{1}_{L^{(1)}}^T\otimes \mathbf{I}_{\boldsymbol{K}}$ de Almeidá@t)al $\!\!\!\!\! \otimes \mathbf{I}_{\boldsymbol{K}}$ KCAP2006 – June 05, 2006 – p.29

### *Special cases* of constrained Block-PARAFAC

Special case 1: Far-field reflections

$$
(a_{m,1}^{(q)} \approx \cdots \approx a_{m,L(q)}^{(q)} = a_m^{(q)}, \quad q = 1, \ldots, Q)
$$

$$
x_{m,n,p}=\sum_{q=1}^Q a_m^{(q)}\sum_{k=1}^K h_{p,k}^{\prime(q)}s_{n,k}^{(q)}+v_{m,n,p},\quad \text{with}\quad h_{p,k}^{\prime(q)}=\sum_{l^{(q)}=1}^{L^{(q)}} b_{l^{(q)}}^{(q)}g_{l^{(q)},k,p}^{(q)}
$$

\n- Constrained Block-PARAFAC model:\n 
$$
(\mathbf{A}' \in \mathbb{C}^{M \times Q}, \quad \mathbf{S} \in \mathbb{C}^{N \times QK}, \quad \mathbf{H}' \in \mathbb{C}^{P \times QK})
$$
\n
$$
\mathbf{X} = (\mathbf{A}' \boldsymbol{\Psi} \diamond \mathbf{S}) \mathbf{H}'^T + \mathbf{V}, \qquad \boldsymbol{\Psi} = \mathbf{I}_Q \otimes \mathbf{1}_K^T, \quad \boldsymbol{\Phi} = \mathbf{I}_{QK}
$$
\n with\n 
$$
\mathbf{A}' = [\mathbf{a}^{(1)} \cdots \mathbf{a}^{(Q)}], \quad \mathbf{H}' = \mathbf{GBJ}_g,
$$
\n
$$
\mathbf{J}_g = BlockDiag(\mathbf{1}_{L^{(1)}} \otimes \mathbf{I}_K \cdots \mathbf{1}_{L^{(Q)}} \otimes \mathbf{I}_K)
$$
\n
\n

**Remark:** This model arises in [Sidiropoulos&Dimic'01] and [de Baynast&De Lathauwer'03] under different formulations and terminologies

∗ In [Sidiropoulos&Dimic'01]: PARALIND model

∗ In [de Baynast&De Lathauwer'03]: Generalized CP model

### *Special cases* of constrained Block-PARAFAC

Special case 2: Local scattering (small delay spread)  $\left(\max(\tau_{la}) \right) \leq \langle T, q = 1, \ldots, Q, K = 1\right)$ 

$$
x_{m,n,p} = \sum_{q=1}^{Q} \sum_{l^{(q)}=1}^{L^{(q)}} b_{l^{(q)}}^{(q)} a_{m,l^{(q)}}^{(q)} g_{p,l^{(q)}}^{(q)} s_n^{(q)} + v_{m,n,p}
$$

• Constrained Block-PARAFAC model:  $({\bf A} \in \mathbb{C}^{M \times L'}, \quad {\bf S} \in \mathbb{C}^{N \times Q}, \quad {\bf H''} \in \mathbb{C}^{P \times L'}$ 

 $\mathbf{X} = (\mathbf{A} \diamond \mathbf{S} \mathbf{\Phi}) \mathbf{H}^{\prime\prime T} + \mathbf{V}, \quad \mathbf{\Psi} = \mathbf{I}_{L'}, \quad \mathbf{\Phi} = BlockDiag(\mathbf{1}_{L^{(1)}}^{T} \cdots \mathbf{1}_{L^{(Q)}}^{T})$ 

with 
$$
\mathbf{G} = [\mathbf{g}_1^{(1)} \cdots \mathbf{g}_{l^{(q)}}^{(q)} \cdots \mathbf{g}_{L^{(Q)}}^{(Q)}] \in \mathbb{C}^{P \times L'}, \quad \mathbf{H}'' = \mathbf{G}\mathbf{B},
$$

$$
\mathbf{J}_g = BlockDiag(\mathbf{1}_{L^{(1)}} \otimes \mathbf{I}_K \cdots \mathbf{1}_{L^{(Q)}} \otimes \mathbf{I}_K)
$$

**Remark:** This special case was considered in [Sidiropoulos&Liu'01].

## Constrained Block-PARAFAC based receiver

Goal:

- 1) Separate the  $Q$  source contributions (ensure between-block uniqueness)
- 2) Recover each source signal (ensure within-block partial uniqueness)

ALS <sup>+</sup> Subspace+ FA algorithm:

- •• Iterative combination of Alternating Least Squares (ALS), Subspace method, and Finite Alphabet (FA) projection:
	- ∗ ALS <sup>+</sup> FA steps:

Separate the Q source signals;

∗ Subspace step:

Recover the transmitted sequences by fixing <sup>a</sup> rotational ambiguity matrix.

- Same idea of [Sidiropoulos&Dimic'01] and [de Baynast&De Lathauwer'03], but fitting <sup>a</sup> different three-way model.
- Forcing the FA property on the symbol matrix accelerates convergence (although not optimal)

#### Constrained Block-PARAFAC based receiver



 $\Omega$  5 10 15 20 25  $10^{-5}$  $10^{-4}$  $10^{-3}$  $10^{-2}$ <sup>10</sup>−1  $10<sup>0</sup>$ SNR (dB) BER M=2 or 3, N=50, P=12 source 1, M=2 source 2, M=2 source 1, M=3 source 2, M=3 source 2, M=3 (MMSE) source 1:  $\mathsf{L}^{(1)}$ =2 source 2: L<sup>(2)</sup>=3

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# Concluding remarks and perspectives

- • Constrained Block-PARAFAC decomposition: Based on De Lathauwer's block-tensor approach, but formulated using constraint matrices
- • Enjoys between-block uniqueness/resolution and different levels of within-block partial uniqueness
- $\bullet$  Application of constrained Block-PARAFAC to two wireless communication problems: multiantenna coding and blind beamforming
- $\bullet$  Constraint matrices are meaningful in wireless signal processing applications (e.g. multiantenna coding)

#### **Perspectives:**

- •Within-block uniqueness from <sup>a</sup> constrained Block-Tucker3 point of view;
- $\bullet$  Applications aspects:
	- (i) Robustness to under- and over-parameterizations (blind beamforming);
	- (ii) Optimization of the constraint matrices (multiantenna coding)