The constrained Block-PARAFAC decomposition

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Presentation outline

- Motivations and preliminaries
- Constrained Block-PARAFAC formulation
- Some terminology and concepts
- Link: constrained Block-PARAFAC and Block-Tucker3
- Uniqueness issues
- Applications in wireless signal processing
- Concluding remarks and perspectives

Motivations and preliminaries

Acknowledgement:

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Motivations and preliminaries

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- PARAFAC: no interaction between modes, *unique* (without orthogonality constraints);
- Tucker3: complete interaction between modes, nonunique (rotational indeterminacy);
- Mixed PARAFAC-Tucker3 models [Bro'98]:
 - * Constrained interactions involving factors different modes (not as complete as in Tucker3 models);
 - * Arise in some wireless signal processing problems:
 - Multiantenna codings
 - Blind beamforming

Motivations and preliminaries

- Mixed PARAFAC-Tucker3 decompositions:
 - * Thinking "Tucker3-wise": constrained core tensor
 - * Thinking "PARAFAC-wise": constrained factor matrices
- Generalizing/combining PARAFAC and Tucker3 decompositions:
 - * Decomposition in a sum of smaller Tucker3 blocks: [De Lathauwer'05]
 - * Decomposition in a sum of constrained PARAFAC blocks: Special case of [De Lathauwer'05]

• The decomposition in scalar form ($\mathcal{X} \in \mathbb{C}^{I_1 \times I_2 \times I_3}$, Q blocks):

$$x_{i_1,i_2,i_3} = \sum_{q=1}^{Q} \sum_{r_1^{(q)}=1}^{R_1^{(q)}} \sum_{r_2^{(q)}=1}^{R_2^{(q)}} a_{i_1,r_1^{(q)}}^{(q)} b_{i_2,r_2^{(q)}}^{(q)} c_{r_1^{(q)},r_2^{(q)},i_3}^{(q)}$$

Special case of [De Lathauwer'05];

•
$$\{\mathbf{A}^{(q)}\} \in \mathbb{C}^{I_1 \times R_1^{(q)}} \text{ and } \{\mathbf{B}^{(q)}\} \in \mathbb{C}^{I_2 \times R_2^{(q)}}, \{\mathcal{C}^{(q)}\} \in \mathbb{C}^{R_1^{(q)} \times R_2^{(q)} \times I_3}$$

• Set of matrices $\{\mathbf{C}^{(q)}\} \in \mathbb{C}^{I_3 \times R_1^{(q)}R_2^{(q)}}$ defined as:

$$\left[\mathbf{C}^{(q)}\right]_{i_3,(r_1^{(q)}-1)R_2^{(q)}+r_2^{(q)}} = c_{r_1^{(q)},r_2^{(q)},i_3}^{(q)}, \quad q = 1,\dots,Q$$

 Factorization as a sum of constrained PARAFAC blocks [de Almeida et al.'05]:

$$\mathbf{X}_{\cdot\cdot i_3} = \sum_{q=1}^{Q} \left(\mathbf{A}^{(q)} \otimes \mathbf{1}_{R_2^{(q)}}^T \right) D_{i_3}(\mathbf{C}^{(q)}) \left(\mathbf{1}_{R_1^{(q)}}^T \otimes \mathbf{B}^{(q)} \right)^T.$$

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Interaction patterns

• Equivalences:

$$\mathbf{A}^{(q)} \otimes \mathbf{1}_{R_2^{(q)}}^T = (\mathbf{A}^{(q)} \otimes 1)(\mathbf{I}_{R_1^{(q)}} \otimes \mathbf{1}_{R_2^{(q)}}^T) = \mathbf{A}^{(q)}(\underbrace{\mathbf{I}_{R_1^{(q)}} \otimes \mathbf{1}_{R_2^{(q)}}^T}_{\Psi^{(q)}}) = \mathbf{A}^{(q)}\Psi^{(q)};$$

$$\mathbf{1}_{R_{1}^{(q)}}^{T} \otimes \mathbf{B}^{(q)} = (1 \otimes \mathbf{B}^{(q)}) (\mathbf{1}_{R_{1}^{(q)}}^{T} \otimes \mathbf{I}_{R_{2}^{(q)}}) = \mathbf{B}^{(q)} (\underbrace{\mathbf{1}_{R_{1}^{(q)}}^{T} \otimes \mathbf{I}_{R_{2}^{(q)}}}_{\mathbf{\Phi}^{(q)}}) = \mathbf{B}^{(q)} \Phi^{(q)};$$

• Constraint matrices:

$$\Psi^{(q)} = \mathbf{I}_{R_1^{(q)}} \otimes \mathbf{1}_{R_2^{(q)}}^T, \qquad \Phi^{(q)} = \mathbf{1}_{R_1^{(q)}}^T \otimes \mathbf{I}_{R_2^{(q)}}$$

• The sets $\{\Psi^{(1)}, \ldots, \Psi^{(Q)}\}$ and $\{\Phi^{(1)}, \ldots, \Phi^{(Q)}\}$ reveal the interaction patterns within the different blocks;

• Factorization using the constraint matrices

$$\mathbf{X}_{..i_{3}} = \sum_{q=1}^{Q} \mathbf{A}^{(q)} \boldsymbol{\Psi}^{(q)} D_{i_{3}}(\mathbf{C}^{(q)}) (\mathbf{B}^{(q)} \boldsymbol{\Phi}^{(q)})^{T}.$$

• Block factor matrices:

$$\mathbf{A} = [\mathbf{A}^{(1)}, \dots, \mathbf{A}^{(Q)}] \in \mathbb{C}^{I_1 \times R_1}$$
$$\mathbf{B} = [\mathbf{B}^{(1)}, \dots, \mathbf{B}^{(Q)}] \in \mathbb{C}^{I_2 \times R_2}$$
$$\mathbf{C} = [\mathbf{C}^{(1)}, \dots, \mathbf{C}^{(Q)}] \in \mathbb{C}^{I_3 \times R_3},$$

$$R_1 = \sum_{q=1}^Q R_1^{(q)}, \quad R_2 = \sum_{q=1}^Q R_2^{(q)}, \quad R_3 = \sum_{q=1}^Q R_1^{(q)} R_2^{(q)}.$$

Block constraint matrices:

$$\Psi = BlockDiag(\Psi^{(1)}\cdots\Psi^{(Q)}) \quad (R_1 \times R_3)$$

$$\Phi = BlockDiag(\Phi^{(1)}\cdots\Phi^{(Q)}) \quad (R_2 \times R_3)$$

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Compact matrix-slice form:

$$\mathbf{X}_{\cdot \cdot i_3} = \mathbf{A} \boldsymbol{\Psi} D_{i_3}(\mathbf{C}) (\mathbf{B} \boldsymbol{\Phi})^T.$$

• Unfolded matrices:

 $\mathbf{X}_1 = (\mathbf{C} \diamond \mathbf{A} \boldsymbol{\Psi}) (\mathbf{B} \boldsymbol{\Phi})^T, \quad \mathbf{X}_2 = (\mathbf{B} \boldsymbol{\Phi} \diamond \mathbf{C}) (\mathbf{A} \boldsymbol{\Psi})^T, \quad \mathbf{X}_3 = (\mathbf{A} \boldsymbol{\Psi} \diamond \mathbf{B} \boldsymbol{\Phi}) \mathbf{C}^T$

Related to PARALIND models [Bro-Harsh-Sid'05]

 Expansion using tensor products of canonical vectors: Goal: Justify the introduction of the constraint matrices [de Almeida et al.'06]

$$\mathbf{X}_{3} = \sum_{i_{1}=1}^{I_{1}} \sum_{i_{2}=1}^{I_{2}} \sum_{i_{3}=1}^{I_{3}} x_{i_{1},i_{2},i_{3}} (\mathbf{e}_{i_{1}}^{(I_{1})} \otimes \mathbf{e}_{i_{2}}^{(I_{2})}) \mathbf{e}_{i_{3}}^{(I_{3})T}$$

$$\mathbf{X}_{3} = \sum_{i_{1}=1}^{I_{1}} \sum_{i_{2}=1}^{I_{2}} \sum_{i_{3}=1}^{I_{3}} \sum_{q=1}^{Q} \sum_{r_{1}=1}^{R_{1}} \sum_{r_{2}=1}^{R_{2}} a_{i_{1},r_{1}}^{(q)} b_{i_{2},r_{2}}^{(q)} c_{r_{1},r_{2},i_{3}}^{(q)} (\mathbf{e}_{i_{1}}^{(I_{1})} \otimes \mathbf{e}_{i_{2}}^{(I_{2})}) \mathbf{e}_{i_{3}}^{(I_{3})T}$$

Some terminology and concepts

What can be said about constrained Block-PARAFAC ?

- Factorization of a three-way array in a sum of Q constrained PARAFAC blocks, everyone of them being a function of three component matrices $\mathbf{A}^{(q)}, \mathbf{B}^{(q)}$ and $\mathbf{C}^{(q)}$.
- Within the same PARAFAC block, it is permitted that columns of different component matrices are linearly combined to generate the three-way data.
- The interaction pattern is defined by the matrices $\Psi^{(q)}$ and $\Phi^{(q)}$ and may differ from block to block.
- No interaction takes place between blocks.

Some terminology and concepts

"Between-block" *versus* "Within-block" uniqueness: [Terms coined by Harshman]

Uniqueness concepts interpreted in two ways:

* Between-block uniqueness: synonym of separability of the Q blocks. Independent of the interaction structure.

* Within-block uniqueness: unique determination of the three component matrices of the corresponding block (up to permutation and scaling). Dependent of the particular interaction structure.

- Connection with "partial" uniqueness concepts:
 - * PARAFAC case [Harshman'72] [ten Berge'04] [Bro-Harsh-Sid'05]:

"When non-unique solutions occur ... uniqueness can partially or completely "break down"..." [Harshman'72]

* Constrained Block-PARAFAC case:

Uniqueness can break down "in parts" (within a block)... but also "between blocks"!

Constrained Block-PARAFAC *linked to* Block-Tucker3

 Constrained Block-PARAFAC can be approached to Tucker3 analysis [Kiers&Smilde'98] [ten Berge&Smilde'02]:

Proposition: The constrained Block-PARAFAC decomposition is equivalent to a "constrained Block-Tucker3" one, where the unfolded matrices of the every core tensor block are column-wise orthogonal, i.e., the inner product of any two distinct columns of every unfolded core matrix is equal to zero.

• The link relies on the concept of block Khatri-Rao product $|\otimes|$: $\mathbf{A} |\otimes| \mathbf{B} = [\mathbf{A}^{(1)} \otimes \mathbf{B}^{(1)}, \cdots, \mathbf{A}^{(Q)} \otimes \mathbf{B}^{(Q)}].$

$$\begin{aligned} \mathbf{X}_{3} &= (\mathbf{A} \boldsymbol{\Psi} \diamond \mathbf{B} \boldsymbol{\Phi}) \mathbf{C}^{T} = (\mathbf{A} \mid \otimes \mid \mathbf{B}) F(\boldsymbol{\Psi}, \boldsymbol{\Phi}) \mathbf{C}^{T}. \\ F(\boldsymbol{\Psi}, \boldsymbol{\Phi}) &= BlockDiag(\underbrace{\boldsymbol{\Psi}^{(1)} \diamond \boldsymbol{\Phi}^{(1)}}_{\mathbf{I}_{R_{3}^{(1)}}} \cdots \underbrace{\boldsymbol{\Psi}^{(Q)} \diamond \boldsymbol{\Phi}^{(Q)}}_{\mathbf{I}_{R_{3}^{(Q)}}}) \\ &\Rightarrow \mathbf{X}_{3} &= (\mathbf{A} \mid \otimes \mid \mathbf{B}) \mathbf{G}_{3} \mathbf{C}^{T}, \quad \mathbf{G}_{3} = \mathbf{I}_{R_{3}} \end{aligned}$$

(Constrained Block-Tucker3 decomp.)

Constrained Block-PARAFAC *linked to* Block-Tucker3

• Unfolded matrices \mathbf{X}_1 and \mathbf{X}_2 :

$$\mathbf{X}_1 = (\mathbf{C} \mid \otimes \mid \mathbf{A}) \mathbf{G}_1 \mathbf{B}^T, \qquad \mathbf{X}_2 = (\mathbf{B} \mid \otimes \mid \mathbf{C}) \mathbf{G}_2 \mathbf{A}^T,$$

• Unfolded block-cores G₁ and G₂:

$$\begin{split} \mathbf{G}_{1} &= BlockDiag(\mathbf{G}_{1}^{(1)}\cdots\mathbf{G}_{1}^{(Q)}) \in \mathbb{C}^{R'\times R_{2}}, \\ \mathbf{G}_{2} &= BlockDiag(\mathbf{G}_{2}^{(1)}\cdots\mathbf{G}_{2}^{(Q)}) \in \mathbb{C}^{R''\times R_{1}}, \\ R' &= \sum_{q=1}^{Q} R_{1}^{(q)}R_{3}^{(q)}, \quad R'' = \sum_{q=1}^{Q} R_{2}^{(q)}R_{3}^{(q)} \\ \mathbf{G}_{1}^{(q)} &= (\mathbf{I}_{R_{3}^{(q)}} \diamond \Psi^{(q)}) \Phi^{(q)T}, \quad \mathbf{G}_{2}^{(q)} = (\Phi^{(q)} \diamond \mathbf{I}_{R_{3}^{(q)}}) \Psi^{(q)T} \\ \mathsf{Are} \ \mathbf{G}_{1}^{(q)} \ \text{and} \ \mathbf{G}_{2}^{(q)} \ \text{column-wise orthogonal } ? \end{split}$$

Constrained Block-PARAFAC *linked to* Block-Tucker3

• We have:

$$\begin{aligned} \mathbf{G}_{1}^{(q)T}\mathbf{G}_{1}^{(q)} &= \mathbf{\Phi}^{(q)}\mathbf{\Phi}^{(q)T} = R_{1}^{(q)}\mathbf{I}_{R_{2}^{(q)}} \\ \mathbf{G}_{2}^{(q)T}\mathbf{G}_{2}^{(q)} &= \mathbf{\Psi}^{(q)}\mathbf{\Psi}^{(q)T} = R_{2}^{(q)}\mathbf{I}_{R_{1}^{(q)}} \end{aligned}$$

• Column-wise orthogonality also for **G**₁ and **G**₂

Constraint matrices from a PARAFAC perspective give rise to orthogonal tensor cores from a Tucker3 perspective

- Uniqueness proof of constrained Block-PARAFAC relies on Harshman's original proof of "minimum conditions" for PARAFAC [Harshman'72].
- The proof sheds light on the between-block resolution/separability for constrained Block-PARAFAC.
- Within-block uniqueness can be studied separately for each block, possibly taking special (within-block) structures into account.
- Different levels of "partial" uniqueness are possible for constrained Block-PARAFAC

Theorem: Assuming full rank $\mathbf{A}^{(q)} \in \mathbb{C}^{I_1 \times R_1^{(q)}}$, $\mathbf{B}^{(q)} \in \mathbb{C}^{I_2 \times R_2^{(q)}}$ and $\mathbf{C}^{(q)} \in \mathbb{C}^{I_3 \times R_1^{(q)} R_2^{(q)}}$, $q = 1, \ldots, Q$, and linear independency of every set $\{\mathbf{A}^{(1)}, \ldots, \mathbf{A}^{(Q)}\}$, $\{\mathbf{B}^{(1)}, \ldots, \mathbf{B}^{(Q)}\}$ and $\{\mathbf{C}^{(1)}, \ldots, \mathbf{C}^{(Q)}\}$, if:

$$I_1 I_2 \ge \sum_{q=1}^Q R_1^{(q)} R_2^{(q)}, \quad I_1 I_3 \ge \sum_{q=1}^Q R_2^{(q)}, \quad I_2 I_3 \ge \sum_{q=1}^Q R_1^{(q)}.$$

between-block uniqueness is achieved and $\overline{\mathbf{A}} = \mathbf{AT}_a$, $\overline{\mathbf{B}} = \mathbf{BT}_b$ and $\overline{\mathbf{C}} = \mathbf{CT}_c$ (up to permutation ambiguities).

$$\begin{aligned} \mathbf{T}_{a} &= BlockDiag(\mathbf{T}_{a}^{(1)}\cdots\mathbf{T}_{a}^{(Q)}), \\ \mathbf{T}_{b} &= BlockDiag(\mathbf{T}_{b}^{(1)}\cdots\mathbf{T}_{b}^{(Q)}), \\ \mathbf{T}_{c} &= BlockDiag(\mathbf{T}_{c}^{(1)}\cdots\mathbf{T}_{c}^{(Q)}), \end{aligned}$$

$$\left(\mathbf{T}_{a}^{(q)} \otimes \mathbf{T}_{b}^{(q)}\right)^{-1} = \mathbf{T}_{c}^{(q)T}, \quad q = 1, \dots, Q$$

- Rotational freedom confined within the blocks; (due to block-diagonal structure of T_a , T_b and T_c)
- Within-block rotational freedom is constrained; (not as complete as for Tucker3)
- Recovering of complete within-block uniqueness (*q*-th block): * If $\mathbf{C}^{(q)}$ is known $\Rightarrow \mathbf{T}_{a}^{(q)} \otimes \mathbf{T}_{b}^{(q)} = \mathbf{I};$
 - * If rotational indeterminacy $\mathbf{T}_{c}^{(q)}$ is fixed;
- Partial uniqueness arises if a subset of $\{\mathbf{T}_a^{(1)}, \dots, \mathbf{T}_a^{(Q)}\}$ or $\{\mathbf{T}_b^{(1)}, \dots, \mathbf{T}_b^{(Q)}\}$ is fixed.

Blocks with equal interaction patterns

$$R_1^{(1)} = \ldots = R_1^{(Q)} = \overline{R}_1$$
 and $R_2^{(1)} = \ldots = R_2^{(Q)} = \overline{R}_2$

• Equivalent necessary condition:

$$\min\left(\lfloor \frac{I_1 I_2}{\overline{R}_1 \overline{R}_2} \rfloor, \lfloor \frac{I_1 I_3}{\overline{R}_2} \rfloor, \lfloor \frac{I_2 I_3}{\overline{R}_1} \rfloor\right) \ge Q.$$

• For $\overline{R}_1 = \overline{R}_2 = 1$ (standard PARAFAC) the above condition reduces to the necessary uniqueness conditions of [Liu-Sid'01].

Partial uniqueness in constrained Block-PARAFAC

- Some blocks can be uniquely determined, while the remaining ones are either nonunique or partially unique
 ⇒ (breaking down of uniqueness between blocks)
- For the remaining (no strictly unique) blocks:

Situation 1: Within-block nonuniqueness

All the corresponding component matrices affected by unknown rotational indeterminacy;

Situation 2: Within-block partial uniqueness

Some component matrices (or a subset of their columns) uniquely determined \Rightarrow (breaking down of uniqueness within a block)

Partial uniqueness in constrained Block-PARAFAC

Example 1:

$$\begin{split} &Q = 3 \text{ blocks} \\ \{R_1^{(1)}, R_2^{(1)}\} = \{1, 1\}, \quad \{\mathbf{a}^{(1)}, \mathbf{b}^{(1)}, \mathbf{c}^{(1)}\} \\ \{R_1^{(2)}, R_2^{(2)}\} = \{2, 2\}, \quad \{\mathbf{A}^{(2)}, \mathbf{B}^{(2)}, \mathbf{C}^{(2)}\} \\ \{R_1^{(3)}, R_2^{(3)}\} = \{1, 2\}, \quad \{\mathbf{a}^{(3)}, \mathbf{B}^{(3)}, \mathbf{C}^{(3)}\} \end{split}$$

Block-constraint matrices:

$$\boldsymbol{\Psi} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}, \quad \boldsymbol{\Phi} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Block 1: *unique* / Block 2: *nonunique* / Block 3: *partially unique* $/ (\mathbf{T}_a^{(2)} \otimes \mathbf{T}_b^{(2)})^{-1} = \mathbf{T}_c^{(2)T} / \mathbf{T}_b^{(3)T} = \mathbf{T}_c^{(3)-1}$

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Partial uniqueness in constrained Block-PARAFAC

Example 2:

$$\begin{split} &Q = 3 \text{ blocks} \\ \{R_1^{(1)}, R_2^{(1)}\} = \{1, 2\}, \quad \{\mathbf{a}^{(1)}, \mathbf{B}^{(1)}, \mathbf{C}^{(1)}\} \\ \{R_1^{(2)}, R_2^{(2)}\} = \{1, 2\}, \quad \{\mathbf{a}^{(2)}, \mathbf{B}^{(2)}, \mathbf{C}^{(2)}\} \\ \{R_1^{(3)}, R_2^{(3)}\} = \{1, 2\}, \quad \{\mathbf{a}^{(3)}, \mathbf{B}^{(3)}, \mathbf{C}^{(3)}\} \end{split}$$

Block-constraint matrices: $\Psi = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}, \quad \Phi = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$

- \Rightarrow Partial uniqueness in all the blocks
- \Rightarrow Complete uniqueness in the first-mode

This case coincides with the "FIA PARALIND model" [Bro-Harsh-Sid'05]

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Applications in Wireless Signal Processing

 Some previous works using PARAFAC modeling in wireless communications:

(DS-CDMA, OFDM, blind beamforming, multiantenna (MIMO) systems,...)

[Sidiropoulos et al.'00-1][Sidiropoulos et al.'00-2][Sidiropoulos&Dimic'01],[Sidiropoulos&Liu'01][Sidiropoulos&Budampati'02][Jiang&Sidiropoulos'03][de Baynast&De Lathauwer'03][de Baynast et al.'03][De Lathauwer'05]

- Two classes of wireless communication problems formulated using constrained Block-PARAFAC modeling:
 - * Multiantenna coding

(with spatial spreading and single-antenna multiplexing)

Blind beamforming

(under specular propagation and large delay spread)

 Constrained Block-PARAFAC structure arises in some of previous works while generalizing some previously proposed three-way models

Application 1: Multiantenna coding





Three-way array dimensions:

 $I_1 = M_R$: Nb. of receive antennas

 $I_2 = N$: Nb. of time-slots

 $I_3 = P$: Nb. of coded symbols per time-slot (code length)

Model parameters:

Q: Nb. of transmission groups (or users to be served) $R_1^{(q)} = L^{(q)}$: Nb. spatially-multiplexed signals $R_2^{(q)} = M_T^{(q)}$: Nb. of spreading transmit antennas A. de Almeida et al. / TRICAP2006 – June 05, 2006 – p.22

Application 1: Multiantenna coding



Decomposition of the received signal as a three-way array:

$$x_{m_R,n,p} = \sum_{q=1}^{Q} \sum_{m_T^{(q)}=1}^{M_T^{(q)}} h_{m_R,m_T^{(q)}}^{(q)} \sum_{l^{(q)}=1}^{L^{(q)}} s_{n,l^{(q)}}^{(q)} w_{m_T^{(q)},l^{(q)},p}^{(q)} + v_{m_R,n,p}$$

$$\begin{split} x_{m_R,n,p} &= [\mathcal{X}]_{m_R,n,p}: \text{ received signal} \\ h_{m_R,m_T^{(q)}}^{(q)} &= [\mathbf{H}^{(q)}]_{m_R,m_T^{(q)}}: \text{ q-th MIMO channel} \\ s_{n,l^{(q)}}^{(q)} &= [\mathbf{S}^{(q)}]_{n,l^{(q)}}: \text{ transmitted symbols (during the n-th time-slot)} \\ w_{m_T^{(q)},l^{(q)},p}^{(q)} &= [\mathbf{W}^{(q)}]_{p,(l^{(q)}-1)M_T^{(q)}+l^{(q)}}: \text{ coding/multiplexing tensor} \end{split}$$

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Application 1: Multiantenna coding

 $\begin{array}{l} * \ L' = L^{(1)} + \cdots + L^{(Q)}: \quad \mbox{total number of multiplexed signals} \\ * \ M'_T = M^{(1)}_T + \cdots + M^{(Q)}_T: \quad \mbox{total number of transmit antennas} \\ * \ R' = L^{(1)} M^{(1)}_T + \cdots + L^{(Q)} M^{(Q)}_T: \quad \mbox{number of columns of } \mathbf{W} \end{array}$

• Constrained Block-PARAFAC model: $(\mathbf{H} \in \mathbb{C}^{M_R \times M'_T}, \mathbf{S} \in \mathbb{C}^{N \times L'}, \mathbf{W} \in \mathbb{C}^{P \times R'})$

$$\mathbf{X} = (\mathbf{H} \boldsymbol{\Psi} \diamond \mathbf{S} \boldsymbol{\Phi}) \mathbf{W}^T + \mathbf{V}, \qquad \mathbf{W} \mathbf{W}^H = M_T' \mathbf{I}_P$$

 Constrained Block-PARAFAC model covers some multi-antenna coding schemes as special cases:

$$* L^{(q)} = M_T^{(q)} = 1, \quad Q > 1:$$

Reduces to the multiantenna code of [Sidiropoulos&Budampati'02]

$$*Q = 1, \quad L^{(q)} > 1, M_T^{(q)} > 1:$$

Takes the form of the multiantenna code of [Hassibi'02]

Constraint matrices: *Physical interpretation*

- Ψ and Φ can be seen as *symbol-to-antenna loading matrices*
- Reveal the joint spreading-multiplexing pattern considered at the transmitter, for each transmission group;
- By configuring the joint pattern of 1's and 0's of these matrices \rightarrow different multiantenna coding schemes can be constructed

Example:

 $\overline{M}'_T = 3$ transmit antennas, Q = 2 Tx groups.

Spreading-multiplexing structures: $(M_T^{(1)}, L^{(1)}) = (2, 1)$ and $(M_T^{(2)}, L^{(2)}) = (1, 3)$.

$$\boldsymbol{\Psi} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 \end{bmatrix} \in \mathbb{C}^{M'_T \times R'}, \quad \boldsymbol{\Phi} = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \in \mathbb{C}^{L' \times R'}$$

1) Rows of Ψ reveal the spatial multiplexing factor

 \Rightarrow nb. of symbols simultaneously loaded at the same transmit antenna

- 2) Rows of Φ reveal the spatial spreading factor
 - \Rightarrow nb. of transmit antennas simultaneously transmitting the same symbol

Constraint matrices: *Physical interpretation*

Joint spreading-multiplexing pattern: The matrix product $\Psi \Phi^T$

$$\boldsymbol{\Psi} \boldsymbol{\Phi}^{T} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix} \in \mathbb{C}^{M'_{T} \times L'}$$

- Reading $\Psi \Phi^T$ column-wise (for a fixed row):
 - * check for the nb. of data-streams multiplexed at a given antenna
- Reading $\Psi \Phi^T$ row-wise (for a fixed column):
 - * check for the nb. of antennas spreading a given data-stream

Remark: Symbol-to-antenna allocation obtained by permuting the columns of the constraint matrices Ψ and Φ . Important in spatially correlated channels

Constrained Block-PARAFAC based multi-

antenna receiver

	Scheme 1	Scheme 2	Scheme 3
$(M^{(1)}, L^{(1)})$	(1,4)	(1,2)	(1,1)
$(M^{(2)}, L^{(2)})$	(2,1)	(2,1)	(2,1)

Rate (q-th group) = $(L^{(q)}/P)log_2(\mu)$ bits/channel use



Application 2: Blind Beamforming



Three-way array dimensions:

 $I_1 = M$: Nb. of receiver antennas

 $I_2 = N$: Nb. of symbols periods

 $I_3 = P$: Oversampling factor (nb. of samples/symbol period)

Model parameters:

Q: Nb. of source signals $R_1^{(q)} = L^{(q)}$: Nb. of multipaths (q-th source); $L' = L^{(1)} + \dots + L^{(Q)}$ $R_2^{(q)} = K$: Temporal support of the convolutive channel (common for all sources)

Application 2: Blind Beamforming

Decomposition of the received signal as a three-way array:

$$\begin{split} x_{m,n,p} &= \sum_{q=1}^{Q} \sum_{l^{(q)}=1}^{L^{(q)}} b_{l^{(q)}}^{(q)} a_{m,l^{(q)}}^{(q)} \sum_{k=1}^{K} s_{n,k}^{(q)} g_{l^{(q)},k,p}^{(q)} + v_{m,n,p} \\ x_{m,n,p} &= [\mathcal{X}]_{m,n,p}: \text{ received signal} \\ b_{l^{(q)}}^{(q)} &= [Diag(\mathbf{B}^{(q)})]_{l^{(q)},l^{(q)}}: \text{ multipath gains/amplitudes} \\ a_{m,l^{(q)}}^{(q)} &= a_{m}^{(q)}(\theta_{l^{(q)}}) = [\mathbf{A}^{(q)}]_{m,l^{(q)}} \text{ array response (Vandermonde structure)} \end{split}$$

 $g_{l(q),k,p}^{(q)} = g(k-1+(p-1)/P - \tau_{l(q)}) = [\mathbf{G}^{(q)}]_{p,(l^{(q)}-1)K+k}$ pulse shape $s_{n,k}^{(q)} = [\mathbf{S}^{(q)}]_{n,k}$: transmitted symbols (Toeplitz structure)

Constrained Block-PARAFAC model: $(\mathbf{A} \in \mathbb{C}^{M \times L'}, \quad \mathbf{S} \in \mathbb{C}^{N \times QK}, \quad \mathbf{H} \in \mathbb{C}^{P \times L'K})$

 $b_{l(q)}^{(q)}$

$$\mathbf{X} = (\mathbf{A} \boldsymbol{\Psi} \diamond \mathbf{S} \boldsymbol{\Phi}) \mathbf{H}^T + \mathbf{V}, \quad \mathbf{H} = \mathbf{G} (\mathbf{B} \otimes \mathbf{I}_K)$$
$$\mathbf{\Psi} = BlockDiag(\mathbf{I}_{L^{(1)}} \otimes \mathbf{1}_K^T \cdots \mathbf{I}_{L^{(Q)}} \otimes \mathbf{1}_K^T)$$
$$\mathbf{\Phi} = BlockDiag(\mathbf{1}_{L^{(1)}}^T \otimes \mathbf{I}_{K \text{ de'All Height (a)}} \otimes \mathbf{1}_K^T)$$

Special cases of constrained Block-PARAFAC

Special case 1: Far-field reflections

$$(a_{m,1}^{(q)} \approx \cdots \approx a_{m,L^{(q)}}^{(q)} = a_m^{(q)}, \quad q = 1, \dots, Q)$$

$$x_{m,n,p} = \sum_{q=1}^{Q} a_m^{(q)} \sum_{k=1}^{K} h_{p,k}^{\prime(q)} s_{n,k}^{(q)} + v_{m,n,p}, \quad \text{with} \quad h_{p,k}^{\prime(q)} = \sum_{l^{(q)}=1}^{L^{(q)}} b_{l^{(q)}}^{(q)} g_{l^{(q)},k,p}^{(q)}$$

• Constrained Block-PARAFAC model:

$$(\mathbf{A}' \in \mathbb{C}^{M \times Q}, \mathbf{S} \in \mathbb{C}^{N \times QK}, \mathbf{H}' \in \mathbb{C}^{P \times QK})$$

 $\mathbf{X} = (\mathbf{A}' \mathbf{\Psi} \diamond \mathbf{S}) \mathbf{H}'^T + \mathbf{V}, \mathbf{\Psi} = \mathbf{I}_Q \otimes \mathbf{1}_K^T, \mathbf{\Phi} = \mathbf{I}_{QK}$
with $\mathbf{A}' = [\mathbf{a}^{(1)} \cdots \mathbf{a}^{(Q)}], \mathbf{H}' = \mathbf{GBJ}_g,$
 $\mathbf{J}_g = BlockDiag(\mathbf{1}_{L^{(1)}} \otimes \mathbf{I}_K \cdots \mathbf{1}_{L^{(Q)}} \otimes \mathbf{I}_K)$

Remark: This model arises in [Sidiropoulos&Dimic'01] and [de Baynast&De Lathauwer'03] under different formulations and terminologies

* In [Sidiropoulos&Dimic'01]: PARALIND model

* In [de Baynast&De Lathauwer'03]: Generalized CP model

Special cases of constrained Block-PARAFAC

Special case 2: Local scattering (small delay spread) $(max(\tau_{lq}) << T, q = 1, ..., Q, K = 1)$

$$x_{m,n,p} = \sum_{q=1}^{Q} \sum_{l^{(q)}=1}^{L^{(q)}} b_{l^{(q)}}^{(q)} a_{m,l^{(q)}}^{(q)} g_{p,l^{(q)}}^{(q)} s_n^{(q)} + v_{m,n,p}$$

• Constrained Block-PARAFAC model: $(\mathbf{A} \in \mathbb{C}^{M \times L'}, \mathbf{S} \in \mathbb{C}^{N \times Q}, \mathbf{H}'' \in \mathbb{C}^{P \times L'})$

 $\mathbf{X} = (\mathbf{A} \diamond \mathbf{S} \mathbf{\Phi}) \mathbf{H}^{\prime \prime T} + \mathbf{V}, \quad \mathbf{\Psi} = \mathbf{I}_{L'}, \quad \mathbf{\Phi} = BlockDiag(\mathbf{1}_{L^{(1)}}^T \cdots \mathbf{1}_{L^{(Q)}}^T)$

with
$$\mathbf{G} = [\mathbf{g}_1^{(1)} \cdots \mathbf{g}_{l^{(q)}}^{(q)} \cdots \mathbf{g}_{L^{(Q)}}^{(Q)}] \in \mathbb{C}^{P \times L'}, \quad \mathbf{H}'' = \mathbf{GB},$$

 $\mathbf{J}_g = BlockDiag(\mathbf{1}_{L^{(1)}} \otimes \mathbf{I}_K \cdots \mathbf{1}_{L^{(Q)}} \otimes \mathbf{I}_K)$

Remark: This special case was considered in [Sidiropoulos&Liu'01].

Constrained Block-PARAFAC based receiver

Goal:

- 1) Separate the *Q* source contributions (ensure between-block uniqueness)
- 2) Recover each source signal (ensure within-block partial uniqueness)

ALS + Subspace+ FA algorithm:

- Iterative combination of Alternating Least Squares (ALS), Subspace method, and Finite Alphabet (FA) projection:
 - * ALS + FA steps:

Separate the Q source signals;

* Subspace step:

Recover the transmitted sequences by fixing a rotational ambiguity matrix.

- Same idea of [Sidiropoulos&Dimic'01] and [de Baynast&De Lathauwer'03], but fitting a different three-way model.
- Forcing the FA property on the symbol matrix accelerates convergence (although not optimal)

Constrained Block-PARAFAC based receiver

	angles-of-arrival	time-delays
Source 1	$(\theta_1^{(1)}, \theta_2^{(1)}) = (-50^\circ, -20^\circ)$	$(\tau_1^{(1)}, \tau_2^{(1)}) = (0, T)$
Source 2	$(\theta_1^{(2)}, \theta_2^{(2)}, \theta_3^{(2)}) = (0^{\circ}, 30^{\circ}, 50^{\circ})$	$(\tau_1^{(1)}, \tau_2^{(1)}, \tau_3^{(1)}) = (0, 0.2T, T)$

M=2 or 3, N=50, P=12 10⁰ source 1: L⁽¹⁾=2 source 2: L⁽²⁾=3 10 10^{-2} BER 10^{-3} source 1, M=2 10^{-4} source 2, M=2 source 1, M=3 source 2, M=3 source 2, M=3 (MMSE) 10^{-5} 15 20 5 10 25 0 SNR (dB)

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Concluding remarks and perspectives

- Constrained Block-PARAFAC decomposition: Based on De Lathauwer's block-tensor approach, but formulated using constraint matrices
- Enjoys between-block uniqueness/resolution and different levels of within-block partial uniqueness
- Application of constrained Block-PARAFAC to two wireless communication problems: multiantenna coding and blind beamforming
- Constraint matrices are meaningful in wireless signal processing applications (e.g. multiantenna coding)

Perspectives:

- Within-block uniqueness from a constrained Block-Tucker3 point of view;
- Applications aspects:
 - (i) Robustness to under- and over-parameterizations (blind beamforming);
 - (ii) Optimization of the constraint matrices (multiantenna coding)